

ERROR PREDICTION METHOD FOR HALFTONE PROCESSING

This application claims the benefit of Taiwan application Serial No. 092117169, filed June 24, 2003, the subject matter of which is incorporated herein by reference.

5

BACKGROUND OF THE INVENTION

Field of the Invention

[0001] The invention relates to a numerical prediction method, and more particularly to an error prediction method.

Description of the Related Art

10 [0002] In an image processing system, the image data often has to be halftone-processed in order to meet various demands of the output apparatuses. Taking a 24-bit image (true color) as an example, the gray-scale values of the red (R), green (G), and blue (B) pixels are represented by 8 bits. However, this representation cannot be directly displayed or printed. For example, each color in the LCD (liquid crystal display) only has 6 bits, and each color for printing only has one bit (three bits are used in an advanced printer). Consequently, the image processing system often needs to convert the image data with a higher bit number (e.g., 8) into another image data with a lower bit number (e.g., 6 or 3), which is the 15 so-called halftone processing.

20

[0003] In the typical halftone processing, the gray-scale value of the pixel is compared to a threshold value. "1" is outputted if the gray-scale value is greater than the threshold value, or otherwise "0" is outputted. Although the method can be easily performed, image distortion may be caused because

5 the error is too large. One of the improved methods is to diffuse the error of each pixel to the adjacent pixels according to a certain proportion, and thus the errors diffused from other pixels also have to be considered when the gray-scale values of the adjacent pixels are calculated. Therefore, the overall error is reduced, and the method is called as the error diffusion

10 method.

[0004] FIG. 1 is a schematic illustration showing the error diffusion method.

The pixels P11, P12 and P21 are adjacent to one another. According to the error diffusion principle, the error of the pixel P11 may be diffused to the pixels P12 and P21 according to a certain proportion (e.g., 50%), respectively.

15 When the gray-scale values of the pixels P12 and P21 are calculated, the diffused errors from the pixel P11 have to be considered. In order to make the error diffusion condition be easily distinguished, the error of the pixel outputted along the horizontal axis (x-axis) direction is referred to as a transversal error EX, and the error of the pixel outputted along the vertical axis

20 (y-axis) direction is referred to as a longitudinal error EY.

[0005] FIG. 2 shows the implementation condition of the error diffusion method for the image data. The image data 200 is a full image composed of plural adjacent image rows, wherein only two rows are representatively

illustrated in the drawing. If the resolution of the image data 200 is 1024×768, it means that the image data has 768 image rows, and each image row has 1024 pixels. When the error diffusion method is performed, the errors of the pixels in each image row will be sequentially diffused along the 5 error diffusion direction. After the errors of all of the pixels have been diffused, the error diffusion for the next image row is performed. Taking this figure as an example, the error of the pixel A in the image row 210 is diffused rightward to the pixel B, the error of the pixel B is calculated by considering the error from the pixel A, and then the calculated error is diffused to the next 10 pixel. The error of each pixel in the image row 210 is generated and diffused outward in this way. After the calculation of the last pixel M is completed, the error diffusion for the image row 220 is performed. The core of the prior art method is to switch to a next image row for the error diffusion operations after 15 all pixels in each image row have been completely diffused. That is, the image row serves as the calculation unit, or the method may be called as a line-based method.

[0006] It is to be noted that the transversal error of each pixel is generated and diffused along the horizontal axis, and the longitudinal error of each pixel is also generated and diffused along the vertical axis. Because the error 20 diffusion has to be performed row by row, the transversal error may be immediately processed after it is diffused to the next pixel, but the longitudinal errors have to be temporarily stored to a memory in advance and the longitudinal errors of the previous image row are considered after the errors of

the next image row are calculated. Taking FIG. 1 as an example, the longitudinal error of the pixel P11 has to be stored in advance, and then be considered when the error of the pixel P21 is calculated. Consequently, the system needs a large memory to store the longitudinal errors of all pixels in a 5 whole image row, which is quite uneconomic to the hardware usage.

SUMMARY OF THE INVENTION

[0007] It is therefore at least an object of the invention to provide an error prediction method capable of solving the problem of calculating the output value when the error of the pixel is unknown.

10 **[0008]** The invention achieves the above-identified object by providing an error diffusion method applied to halftone processing for image data. The image data comprising a plurality of pixels. The method comprising the steps of dividing the image data into a plurality of image blocks; selecting one of the pixels belonging to each of the image blocks as a target pixel, wherein the 15 target pixel is located on the boundary of the corresponding image block; assigning a predicted error to the target pixel; and executing the error diffusion method on the rest of the pixels of the image blocks according to the predicted error of the target pixels of the image blocks.

20 **[0009]** In this error prediction method, the image processing direction is not restricted to the conventional horizontal direction. Instead, the vertical direction processing also may be implemented. In addition, multiple image

blocks also may be processed simultaneously as long as the pixels on the boundaries of the image blocks are set as the target pixels and the output values thereof are calculated using the error prediction method.

[0010] Other objects, features, and advantages of the invention will 5 become apparent from the following detailed description of the preferred but non-limiting embodiments. The following description is made with reference to the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011] FIG. 1 is a schematic illustration showing the error diffusion method.

10 [0012] FIG. 2 shows the implementation condition of the error diffusion method for the image data.

[0013] FIG. 3 is a schematic illustration showing the image data according to one preferred embodiment of the invention.

DETAILED DESCRIPTION OF THE INVENTION

15 [0014] In the above-mentioned error diffusion method, when the output value of some pixel is calculated, the errors diffused from an above pixel and a previous pixel have to be known. In some situations, however, the output values of some pixels have to be calculated when the errors diffused from the outside are not calculated or obtained. At this time, the invention provides an

error prediction method for predicting errors of previous points with respect to these pixels so as to successfully generating the errors thereof and diffusing the errors outward. The pixels that have to be predicted the errors are referred to as target pixels. Of course, in terms of the image data of the 5 entire frame, the number of the target pixels cannot be too great; otherwise the precision of the error diffusion method will be lost, thereby causing the image distortion. In the following, four embodiments for error prediction will be illustrated for explaining the application chances of this invention.

[0015] In a first embodiment, if the output sequence for the calculated 10 errors is from left to right of each image row and then row by row, when the leftmost pixel in each row is calculated, a previous point with respect to the pixel does not exist and its output error has to be predicted or assumed because the leftmost pixel is an initial point. Similarly, when the error of the first image row is calculated, the errors of the previous pixels of the previous 15 image row with respect this image row do not exist and have to be predicted.

[0016] In a second embodiment, if there are N sets of mechanisms for calculating the output values, the N rows of output values may be calculated from left to right simultaneously. As for any one of the N rows, a previous 20 above row of errors has to be referred, so the errors of the n-th row cannot be calculated until the errors of the (n-1)th row have been calculated, and the error prediction of the leftmost pixel of each row is the same as that of the first embodiment.

[0017] In a third embodiment, when the error diffusion method is performed, the frame looks like specific textures because the proportion of the error diffusion is constant. In order to eliminate the phenomenon, inverse diffusion directions for the odd rows and even rows may be adopted. If the odd row is 5 diffused rightward and the even row is diffused leftward, the error predictions of the previous pixels have to be made in the leftmost pixel of the odd row and the rightmost pixel of the even row.

[0018] In a fourth embodiment, if the image data is divided into several image blocks and each image block serves as a calculation unit for error diffusion, then the left and right boundaries of each block encounter the 10 problem of error prediction. At this time, the precision of the error prediction directly influences the quality of the overall frame. FIG. 3 is a schematic illustration showing the image data according to one of the preferred embodiments of the invention. The image data 300 may be defined as 15 several image blocks, and the output of the image block is calculated after the output of the previous image block has been calculated. Taking the image blocks BK11 and BK12 as an example, each block has several (four in this example) image rows, and the error of each pixel in each image row is diffused along the arrow direction. Because the calculation unit of the error 20 diffusion is one image block, the error diffusion has to be turned to a next row after the error of the last pixel of the image row has been calculated. For example, after the output of the last pixel "a" in the image row M1 has been calculated, the output of the pixel "b" in the image row M2, rather than the

output of the pixel "e" in the image block BK12, has to be calculated.

[0019] When the error is predicted, the target pixel of each image block has to be decided in advance, and then the predicted error is assigned to the target pixel. The most convenient and quick way is to set the predicted error 5 to "0", which is very reasonable for the first to third embodiments. However, setting the predicted error to "0" may sometimes cause unsMOOTH connections between boundaries of the image blocks in the fourth embodiment. One way for solving this problem is to set the predicted error as the error of the adjacent to the target pixel in either transversal or longitudinal direction, such 10 as the pixel above the target pixel, wherein the pixel above the target pixel is located on an image row above the target pixel. For example, if the error of pixel "b" is the first point to be calculated in the image row M2 but the error of pixel "f" is not calculated and cannot be diffused to the pixel "b", the error of pixel "a" serves as the predicted error to be diffused to the pixel "b". Thus, 15 the error may be diffused leftward from the starting pixel "b" in the image row M2, wherein the pixel "b" is the so-called target pixel and the pixel "a" is the so-called the last pixel. In the image block BK12, because the to-be-received transversal errors for the first pixels (pixel e, pixel g) from left to right have 20 been calculated from (pixel a, pixel c) in the image block BK11, no prediction has to be made.

[0020] It is to be noted that although the embodiments are illustrated according to the error diffusion in the horizontal direction, the field of the error prediction methods cannot be restricted to the horizontal direction. Instead,

the error diffusion in the vertical direction also may be implemented. In addition, it is possible to process multiple image blocks simultaneously so as to speed up the image processing speed. In this case, the processing may be performed only by prescribing the target pixel of the boundary of each 5 image block and then calculating the error output value of each target pixel using the error prediction method.

[0021] While the invention has been described by way of embodiments, it is to be understood that the invention is not limited thereto. On the contrary, it is intended to cover various modifications and similar arrangements and 10 procedures, and the scope of the appended claims therefore should be accorded the broadest interpretation so as to encompass all such modifications and similar arrangements and procedures.